

Situation 11 CANL Fault: NINE flashes of the status LED

Nine flashes indicates that the system has detected an invalid voltage on the DXBUS CANL line.

To check for this fault, perform a continuity test of the DXBUS harness.



If the harness has continuity on all four pins of the harness the problem could lie in the power module. In this case you will need to replace the power module.

Situation 12 CANH Fault: TEN flashes of the status LED

Ten flashes of the status LED indicates that the system has detected an invalid voltage on the DXBUS CANH line. When this occurs communication is not possible between the RemG80 and the power module.

Check for continuity from the four pins located on one end of the DXBUS harness to the four pins located in the opposite end of the DXBUS harness.



If you do not have continuity, replace the harness, if you do it could be a problem with the power module. If this is the case you will need to replace the power module.

Another cause of this fault would be if the hazard lights were turned on when the Dynamic system was turned on. If this is the case, turn the hazard lights off and cycle the power off and then on again and see if the fault is still occurring.

Situation 13 Stall Timeout Fault: ELEVEN flashes of the status LED

Eleven flashes of the status LED occurs when the motor current has been at, or is close to the current limit for longer than the Stall Timeout Parameter value. The Dynamic system has a feature called a Stall Timeout Parameter, which in turn means that the controller has a time limit in which current from the motors is allowed before the controller faults to protect the motors and control system.

To test if this fault is caused by the wheels binding up, place the power chair in freewheel and see if it rolls freely with no drag from the wheels. If there is a drag the resistance could be caused by an internal gear problem with the motors, or something is binding the wheels. If this is the case replace the component which is binding up and causing the drag.

Another possibility is that the chair is binding up while driving.

This can be caused by operating the power chair while it is bound by an obstacle. The Dynamic controller is designed to protect the motors and electronics by stalling out the chair.



Stall out is when the controller disables the drive functions and displays an error on the status LED.

This can be reset by correcting the source of the fault and cycling the power off and on again.